

**IN THE SPECIFICATION:**

**Please amend the specification beginning on page 24 at line 8 and ending at line 14 as follows:**

When the robot 5 is moving away from the access point 2, the robot 5 can also be allowed to generate a voice message of “I cannot see the access point. Do I have ~~not~~ to go ~~to~~ here?”. As mentioned above, a voice message to be generated from the robot 5 is determined in further consideration of the details of the current action of the robot 5, thus resulting in more natural speech of the robot 5.

**Please amend the specification beginning on page 25, line 1 and ending at line 9 as follows:**

For example, when a refrigerator is placed at the front of the access point 2 as viewed from the robot 5, the user issues an order to prevent such a situation, e.g., says “Take 10 steps to the left”. If a microwave oven placed near the robot 5 is running, the user says, e.g., “Hold on” (and the user turns off the microwave oven). When the robot 5 moves away from the access point 2 and generates a voice message of “I cannot see the access point. Do I have ~~not~~ to go ~~to~~ here?”, the user says “Don't go ~~to~~ there”.

**Please amend the specification beginning on page 25, line 10 and ending at line 21 as follows:**

When the robot 5 receives the above-mentioned speech, the robot 5 recognizes the speech as an instruction. For example, in response to the instruction of “Take 10 steps to the left”, the robot 5 moves to the left only by 10 steps (the operation to move the leg unit 14A to the left by one step and then move the leg unit 14B to the left by one step is repeated 10 times). In response to the instruction of “Hold on” or “Don't go ~~to~~ there”, the robot 5 stops the current action. Prior

to allowing the robot 5 to act in accordance with the user's speech, the robot 5 can generate a voice message indicating that robot 5 has recognized an instruction of the user, e.g., "Yes, understood".